Progarm:

#include <LiquidCrystal.h>

LiquidCrystal lcd(12, 11, 5, 4, 3, 2);

Int distanceThreshold = 0;

Int cm = 0;

Int inches = 0;

Int releNO = 13;

Int inputPir = 8;

Int val = 0;

Int resuldoSensorLDR;

Int sensorLDR = A0;

Int const PINO\_SGAS = A1;

Long readUltrasonicDistance(int triggerPin, int echoPin)

{

pinMode(triggerPin, OUTPUT); digitalWrite(triggerPin, LOW);

delayMicroseconds(2);

digitalWrite(triggerPin, HIGH);

delayMicroseconds(10);

digitalWrite(triggerPin, LOW);

pinMode(echoPin, INPUT);

return pulseIn(echoPin, HIGH);

}

Void setup() {

Lcd.begin(16, 2);

pinMode(releNO, OUTPUT);

pinMode(inputPir, INPUT);

pinMode(sensorLDR, INPUT);

Serial.begin(9600);

}

Void loop() {

distanceThreshold = 350;

cm = 0.01723 \* readUltrasonicDistance(7, 6);

inches = (cm / 2.54);

lcd.setCursor(0,0);

lcd.print(“D:”);

lcd.print(cm);

lcd.print(“cm”);

delay(10);

val = digitalRead(inputPir);

resuldoSensorLDR = analogRead(sensorLDR);

if(resuldoSensorLDR<600)

{

If(val == HIGH)

{

digitalWrite(releNO, HIGH);

lcd.setCursor(0,1);

lcd.print(“L: On “);

delay(5000);

}

Else{

digitalWrite(releNO, LOW);lcd.setCursor(0,1);

lcd.print(“L: Off”);

delay(300);

}

}

Else{ digitalWrite (releNO, LOW);

Serial.println(resuldoSensorLDR);

Delay(500);

Int color = analogRead(PINO\_SGAS);

Lcd.setCursor(8,0);

//lcd.print(“”);

If(color <= 85){

Lcd.print(“G:Low “);

} else if(color <= 120){

Lcd.print(“G:Med “);

} else if(color <= 200){

Lcd.print(“G:High”);

} else if(color <= 300){

Lcd.print(“G:Ext “);

}

Delay(250);